



We're getting the word out about the...

AUSTIN STRATEGIC MOBILITY PLAN

Why do we need a new plan?

- Our current transportation plan, the Austin Metropolitan Area Transportation Plan (AMATP), was adopted in 1995 and needs to be updated to reflect the vision established in Imagine Austin.

What will this plan focus on?

- Expanding the Imagine Austin vision into actionable mobility-related goals and objectives.
- Identifying ways to improve efficiencies in our existing system, manage demand, and strategically add capacity in all modes.
- An integrated approach to planning for all modes of our transportation system.
- Approaching transportation access and mobility as essential to quality of life for Austin residents.
- Adding performance measures that will track the City's progress and ensure accountability.
- Considering technological advances shaping the 21st century transportation system.

Who will be involved?

You, our mobility agency partners, and other regional stakeholders.

Plan Schedule



IMAGINE AUSTIN TRANSPORTATION VISION STATEMENT:

AUSTIN IS MOBILE AND INTERCONNECTED

Austin is **accessible**. Our transportation network provides a wide variety of **options** that are efficient, reliable, and cost-effective to serve the diverse needs and capabilities of our citizens. Public and private sectors work together to **improve air quality** and **reduce congestion** in a collaborative and creative manner.

- Interconnected development patterns support **public transit** and a variety of **transportation choices**, while reducing sprawl, congestion, travel times, and negative impacts on existing neighborhoods.
- Our **integrated transportation system** is well-maintained, minimizes negative impacts on natural resources, and remains affordable for all users.
- Austin promotes **safe** bicycle and pedestrian access with well-designed routes that provide **connectivity** through the greater Austin area. These routes are part of our comprehensive regional transportation network.

Source: Imagine Austin Comprehensive Plan